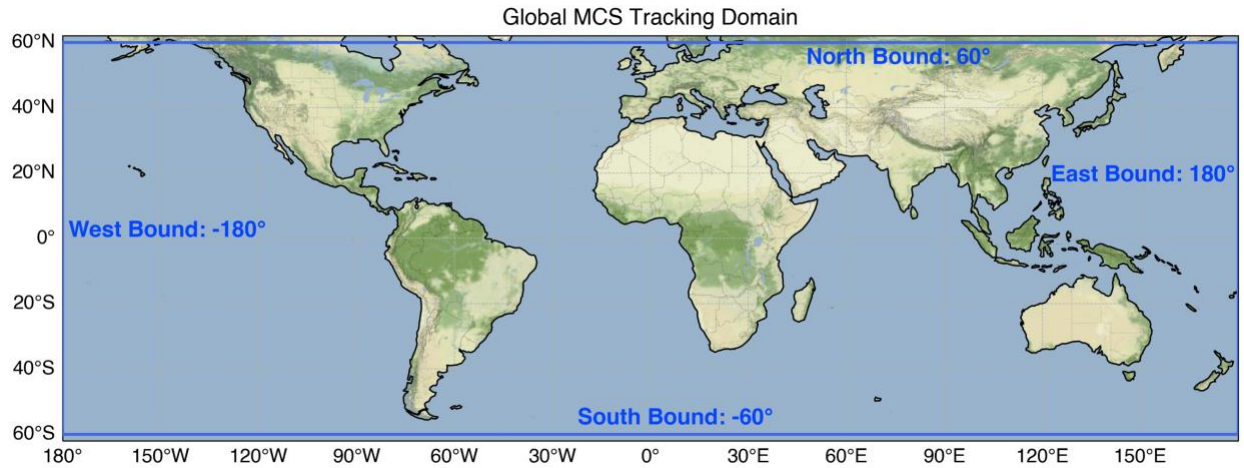


Description of the PyFLEXTRKR MCS Tracking Dataset

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1. Introduction

This documentation explains the Global MCS tracking dataset developed by Feng et al. (2021). The current v2 of the dataset is produced by the Python FLEXible object TRaKeR (PyFLEXTRKR) algorithm (Feng et al., 2023). The period is from June 2000 to December 2020. The geographic coverage is 180°W-180°E, 60°S-60°N.



2. Purpose

The purpose of PyFLEXTRKR is to provide automated identification and lifecycle evolution of individual MCS events, along with a suite of important MCS characteristics including lifetime, infrared brightness temperature (T_b) defined cloud shield (cold cloud cores and surrounding cold anvils) and surface precipitation feature characteristics, movement, and more. PyFLEXTRKR can be applied to observations and model simulations, facilitating their objective and statistical comparisons.

3. MCS Tracking Algorithm

The FLEXTRKR algorithm first identifies and tracks large cold cloud systems (CCSs) associated with deep convection using T_b data, and subsequently identifies MCSs based on collocated precipitation feature (PF) characteristics. A CCS is defined using a detect-and-spread method, where contiguous regions of cold core are expanded to include surrounding cold anvils. An option to use PF to link CCS that share a large PF is provided. For more details of this method see Feng et al. (2018). An MCS is defined as a large CCS ($T_b < x$ K, area $> x$ km²) containing a PF (contiguous area within a CCS with rain rate $> x$ mm h⁻¹) with major axis length $> x$ km, and PF area, PF mean rain rate, PF rain rate skewness, and heavy rain volume ratio exceeding user-defined lifetime-dependent thresholds and persists for at least x hours. All

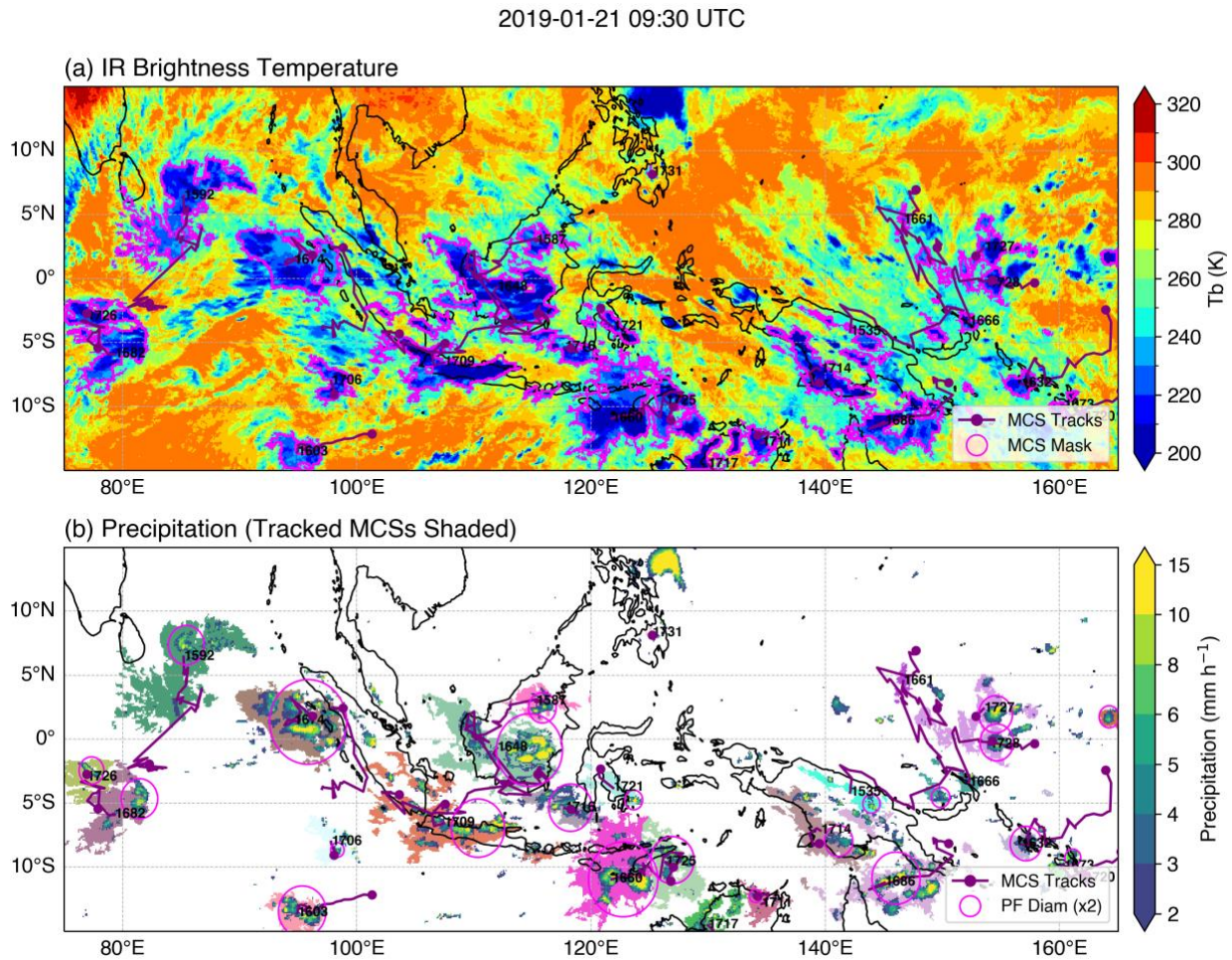
user-defined parameters are set in the config file in yaml format. Most of the key parameters used to define MCS are also recorded in the global attribute of the MCS track statistics data.

4. MCS Data Description

a) Hourly pixel-level data

The MCS tracking pixel-level data are produced on the native grid of the input dataset. The pixel-level data contains full field of T_b , precipitation, CCS cloud object identification, and MCS tracking number. The data file name follows this format “`mcstrack_yyyymmdd_hhmm.nc`”.

Figure 1 shows an example of the pixel-level MCS database over the Maritime Continent. IR brightness temperature (T_b) and precipitation are both full fields from the input dataset. The color shadings behind large clusters of PFs show the MCS masks for individual MCSs. The same color shadings between different times denote the same MCS being tracked.



magenta circles in (b) show the largest PF equivalent diameter (multiplied by 2 for visibility) within an MCS. Animation for this day can be found in https://portal.nersc.gov/project/m1867/mcs_global_v2/MCS_pixeldata_example_animation.mp4.

Table 1. MCS track pixel-level data variables and descriptions.

Variable Name	Dimension	Description
time	time	Epoch time
base_time	time	Epoch time (same as “time”)
lon	lon	Longitude
lat	lat	Latitude
longitude	lat, lon	Longitude of each grid
latitude	lat, lon	Latitude of each grid
tb	time, lat, lon	Brightness temperature (full data)
precipitation	time, lat, lon	Precipitation (full data)
cloudtracknumber	time, lat, lon	MCS cloud track number mask
pcptracknumber	time, lat, lon	MCS PF track number mask. This track number is the same with “cloudtracknumber” except only applied to precipitation.
cloudtracknumber_nomergesplit	time, lat, lon	MCS cloud track number (exclude merge/split clouds)
merge_tracknumbers	time, lat, lon	Number of the MCS track that this cloud merges into
split_tracknumbers	time, lat, lon	Number of the MCS track that this cloud splits from
cloudnumber	time, lat, lon	Number associated with a CCS at a given pixel (not tracked)
cloudtype	time, lat, lon	Grid of cloud type classifications. 1 = core, 2 = cold anvil, 3 = warm anvil, 4 = other

Explanation of each variable in the pixel-level data is provided in **Table 1**. Within each sub-directory of pixel-level data, denoted by the start and end date of a continuous tracking period (e.g., 20140101.0000_20140201.0000), the MCS track number (“*cloudtracknumber*”, and “*pcptracknumber*”) monotonically increases from 1 to X (the maximum number of MCSs tracked during a period). For example, *cloudtracknumber* = 1 within multiple pixel-level data files denotes the first MCS tracked during this period. The MCS track number in “*cloudtracknumber*” and “*pcptracknumber*” is the same, but they differ in areal coverage. “*cloudtracknumber*” is defined using T_b , so it has a larger coverage, usually containing most if not all of the precipitation in the vicinity of the MCS. “*pcptracknumber*” is defined using precipitation, so it has a smaller coverage, only containing the major precipitation features.

Note that the MCS track numbers all start from 1 for each individual tracking periods, i.e., they are not unique across different tracking periods. For example, there will be MCS track number = 1 in both tracking period 20140101.0000_20140201.000 and 20140201.0000_20140301.0000. Because each tracking period are tied to one track file (described below), which contains time and location of each MCSs, they can be distinguished across different tracking periods if one desired to do so. If there is not a single CCS identified in

the entire domain at a given time, or there are significant areas of missing T_b data (e.g., missing satellite scans), there will not be an MCS tracking pixel-level data for that time.

Sub-directory of pixel-level data: [/mcstracking/yyyymmdd.hhmm_YYYYMMDD.HHMM/](#)

b) Track statistics data

The track data contains many variables summarizing the key features (i.e., statistics) of MCSs. Each continuous tracking period correspond to one track file. The data file name follows this format “[mcs_tracks_final_YYYYMMDD.HHMM_YYYYMMDD.HHMM.nc](#)”.

The track data describes the timing, location (e.g., “*meanlat*”, “*meanlon*”), and evolution of each MCS during the tracking period. The variables are organized by [*tracks*, *times*]. The “*tracks*” dimension is the number of MCSs in the tracking period, and the tracks match the track number in the pixel-level data. For example, *tracks* = 0 is the first MCS in the pixel-level data (*cloudtracknumber* = 1, or *pcptracknumber* = 1), and *tracks* = 1 is the second MCS (*cloudtracknumber* = 2, or *pcptracknumber* = 2), ..., etc. The “*times*” dimension is the relative time since an MCS is detected. For example, *times* = 0 is the convection initiation time (defined by the first detection of a CCS from T_b data) of an MCS. A variable named “*base_time*” (Epoch time in seconds since 1970-01-01T00:00:00) with dimension [*tracks*, *times*] designates the time for each MCS track at each time. Combining “*base_time*”, which locates the time of an MCS, and the track index, which corresponds to the “*cloudtracknumber*” mask in the pixel-level data described above, one can link the MCS track data with the exact pixel-level location of the MCS at a given time.

For MCS characteristics, there are generally two types of variables, one derived from IR T_b data, which has two dimensions [*tracks*, *times*]; and another type derived from precipitation data, which has three dimensions [*tracks*, *times*, *nmaxpf*].

Explanation of each variable in the MCS track statistics data is provided in **Table 2**.

Table 2. MCS track statistics hourly data variables and descriptions.

Variable Name	Dimension	Description
track_duration	tracks	Duration of each tracked MCS defined by CCS. This is the longest lifetime of MCS, potentially including times before and after precipitation. Multiply “track_duration” by “time_resolution_hour” (in global attribute) to convert to physical lifetime units.
mcs_duration	tracks	Duration of MCS stage (CCS > MCS area threshold). Multiply by “time_resolution_hour” (in global attribute) to convert to physical lifetime units.
start_basetime	tracks	Start Epoch time of each track
end_basetime	tracks	End Epoch time of each track
start_split_cloudnumber	tracks	Cloud number where this track splits from
end_merge_cloudnumber	tracks	Cloud number where this track merges with

start_status	tracks	Flag indicating how the track starts
end_status	tracks	Flag indicating how the track ends
track_status	tracks, times	Flag indicating evolution / behavior a track. See Table 3 for detailed descriptions.
base_time	tracks, times	Epoch time of each MCS in a track
mcs_status	tracks, times	Flag indicating the status of MCS based on Tb. 1 = Yes, 0 = No.
meanlat	tracks, times	Mean latitude of MCS defined using CCS area
meanlon	tracks, times	Mean longitude of MCS defined using CCS area
core_area	tracks, times	Area of cold cloud core
cold_area	tracks, times	Area of cold anvil
ccs_area	tracks, times	Area of cold cloud shield (CCS)
corecold_mintb	tracks, times	Minimum Tb in core + cold anvil area
corecold_meantb	tracks, times	Mean Tb in core + cold anvil area
core_meantb	tracks, times	Mean Tb in core area
cloudnumber	tracks, times	Cloud number in the corresponding cloudid file
merge_cloudnumber	tracks, times, mergers	Cloud numbers that merge into MCS
split_cloudnumber	tracks, times, mergers	Cloud numbers that split from MCS
merge_ccs_area	tracks, times, mergers	Cold cloud shield area that merge into MCS
split_ccs_area	tracks, times, mergers	Cold cloud shield area that split from MCS
Precipitation Feature (PF) Statistics		
pf_lifetime	tracks	MCS lifetime when a significant PF is present, which can be considered as the active period of the convection.
pf_mcsstatus	tracks, times	Flag indicating the status of MCS based on PF. 1 = Yes, 0 = No
total_rain	tracks, times	Total precipitation under CCS. No cosine latitude weighting is applied.
total_heavyrain	tracks, times	Total heavy precipitation under CCS. No cosine latitude weighting is applied.
rainrate_heavyrain	tracks, times	Mean heavy rain rate under CCS. No cosine latitude weighting is applied.
pf_npf	tracks, times	Number of PF under the CCS
pf_landfrac	tracks, times	Fraction of PF over land
pf_area	tracks, times, nmaxpf	PF area under CCS
pf_lon	tracks, times, nmaxpf	Mean longitude of each PF
pf_lat	tracks, times, nmaxpf	Mean latitude of each PF
pf_lon_centroid	tracks, times, nmaxpf	Centroid longitude of PF
pf_lat_centroid	tracks, times, nmaxpf	Centroid latitude of PF
pf_lon_weightedcentroid	tracks, times, nmaxpf	Rain rate weighted centroid longitude of PF
pf_lat_weightedcentroid	tracks, times, nmaxpf	Rain rate weighted centroid latitude of PF
pf_rainrate	tracks, times, nmaxpf	Mean precipitation rate of each PF
pf_maxrainrate	tracks, times, nmaxpf	Maximum precipitation rate of each PF
pf_accumrain	tracks, times, nmaxpf	Area total precipitation rate of each PF
pf_accumrainheavy	tracks, times, nmaxpf	Area total heavy precipitation of each PF
pf_skewness	tracks, times, nmaxpf	PF pixel-level rain rate skewness
pf_majoraxis	tracks, times, nmaxpf	PF major axis length

pf_minoraxis	tracks, times, nmaxpf	PF minor axis length
pf_aspecratio	tracks, times, nmaxpf	PF aspect ratio (major axis length / minor axis length)
pf_orientation	tracks, times, nmaxpf	Orientation of major axis of PF
pf_eccentricity	tracks, times, nmaxpf	Eccentricity of PF
Movement		
movement_distance	tracks, times	Movement distance along angle movement_theta
movement_speed	tracks, times	Movement speed along angle movement_theta
movement_theta	tracks, times	Movement direction (Caution using this variable! Direction is not defined the same as traditional meteorology wind direction. Use <i>movement_distance_x</i> and <i>movement_distance_y</i> to compute direction instead.)
movement_distance_x	tracks, times	East-West component of movement distance
movement_distance_y	tracks, times	North-South component of movement distance

Table 3. Track status description.

Status	Description
0	Track stops
1	Simple track continuation
2	This is the bigger cloud in simple merger
3	This is the bigger cloud from a simple split that stops at this time
4	This is the bigger cloud from a split and this cloud continues to the next time
5	This is the bigger cloud from a split that subsequently is the big cloud in a merger
13	This cloud splits at the next time step
15	This cloud is the bigger cloud in a merge that then splits at the next time step
16	This is the bigger cloud in a split that then splits at the next time step
18	Merge-split at same time (big merge, splitter, and big split)
21	This is the smaller cloud in a simple merger.
24	This is the bigger cloud of a split that is then the small cloud in a merger
31	This is the smaller cloud in a simple split that stops
32	This is a small split that continues onto the next time step
33	This is a small split that then is the bigger cloud in a merger
34	This is the small cloud in a merger that then splits at the next time step
37	Merge-split at same time (small merge, splitter, big split)
44	This is the smaller cloud in a split that is smaller cloud in a merger at the next time step
46	Merge-split at same time (big merge, splitter, small split)
52	This is the smaller cloud in a split that is smaller cloud in a merger at the next time step
65	Merge-split at same time (smaller merge, splitter, small split)

Two methods to separate tracks that initiate *naturally* from *splitting*, or tracks that end *naturally* from *merging*:

Initiate as split or “naturally”:

1. *start_split_cloudnumber* > 0 means track start as a split
2. *start_status* ≠ 1 or 2 means track start as a split

Possible values for *start_status*: 1, 2, 13, 15, 32, 33, 44, 46.

Possible *start_status* values when *start_split_cloudnumber* > 0 (split) are: 31, 32, 33, 44, 46, 52, 65.

End as merger or “naturally”:

1. *end_merge_cloudnumber* > 0 means track end as a merger
2. *end_status* ≠ 0 or 3 means track end as a merger

Possible values for *end_status*: 0, 3, 21, 24, 34, 37.

Possible *end_status* values when *end_merge_cloudnumber* > 0 (merger) are: 21, 24, 34, 37, 52, 65.

The variables derived from precipitation data contains several (defined by “*nmaxpf*” in the config file) of the largest Precipitation Features (PFs) within each CCS. The “*nmaxpf*” dimension is organized by size, e.g., *nmaxpf* = 0 contains the largest PF at any given time associated with an MCS.

Movement of MCS PFs are estimated using 2-D cross-correlation map between user-defined time-steps (“*lag_for_speed*”) of the MCS PFs. The detail description of the method is provided in Feng et al. (2018).

Sub-directory of track statistics data:

[/stats/mcs_tracks_final_extc_yyyymmdd.hhmm_yyyymmdd.hhmm.nc](#)

c) Linking track statistics data with pixel-level data

Here is an example usage case to link the track statistics data with pixel-level data: where exactly is the MCS feature mask for track #2 at time = 2010-07-01 03:00 UTC? **Figure 2** shows an example on how to link the pixel-level MCS mask with the track statistics data. For a given pixel-level file, the MCS mask values in the variable “*cloudtracknumber*” correspond to the “tracks” dimension in the MCS track statistics file (offset by 1 for 0-based indexing). **Figure 2a** shows two MCSs (track # 2, 3) coexist at 2010-07-01 03:00 UTC. These two MCSs correspond to the “tracks” indices (1, 2) and “times” indices (0, 1) in the track statistics file, because the values in the track statistics “*base_time*” variable (Epoch time) matches the pixel-level file time 2010-07-01 03:00 UTC.

In practice, since both sets of pixel-level and track statistics files contain Epoch time (“*base_time*”), which contains the full date/time (e.g., 2010-07-01T03:00:00), one can simply search for the matching “*base_time*” between track statistics file and a specific pixel-level file to find all the indices of MCS tracks that exist in that hour.

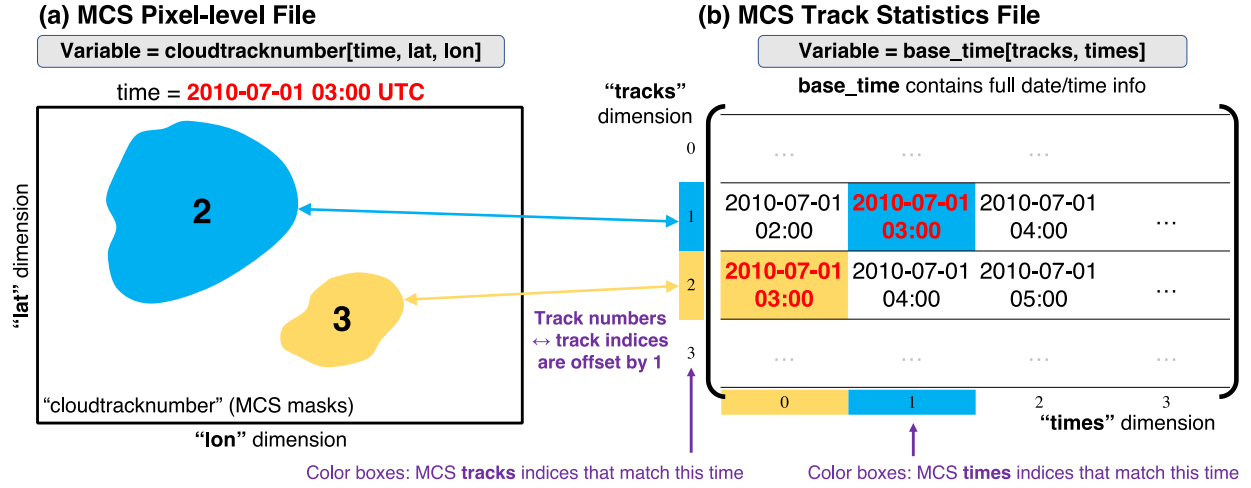


Figure 2. An example to link a track statistics variable to a pixel-level file. (a) MCS pixel-level file, showing variable “*cloudtracknumber*” containing MCS masks at 2010-07-01 03:00 UTC, (b) MCS track statistics file, showing variable “*base_time*” containing the Epoch time of each MCS. The MCS “*cloudtracknumber*” values correspond to the “tracks” indices (offset by 1 for 0-based indexing). For each matching MCS track, the matching time index can be located by matching the “*base_time*” value (Epoch time) with the pixel-level file “time” (Epoch time), shown in red colors (2010-07-01 03:00).

5. Analysis codes

Post-processing and analysis Python Notebooks are available on GitHub:

<https://github.com/FlexTRKR/PyFLEXTRKR/tree/main/Notebooks>

References

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- Feng, Z., Leung, L. R., Houze, R. A., Hagos, S., Hardin, J., Yang, Q., et al. (2018). Structure and Evolution of Mesoscale Convective Systems: Sensitivity to Cloud Microphysics in Convection-Permitting Simulations Over the United States. *Journal of Advances in Modeling Earth Systems*, 10(7), 1470-1494. <https://doi.org/10.1029/2018MS001305>
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